

An automatic fixation of the transport position, carried out by a hydrocylinder 3, which while the rod projects, first, turns a cross-arm 8 around an axis 7 up to the contact with a support 9, is proposed. In doing so a fixer 11 under the action of a twisting spring 13 is in contact with an adjusting screw 15. While the further stroke of the rod is taking place, a fork 5 with a wheel 6 is moved downwards, and the fixer 11 due to a wedge at end thereof enters into an opening on a cramp-iron 16 and under the effect of the spring is kept in the closed position. In order to move the wheels into the working position the rod of the hydrocylinder 3, while it is being drawn in, turns the cross-arm 8 due to free stroke up to the contact with a support 10 and simultaneously with the other end the cross-arm 8 turns the fixer 11 around the axis 12 and removes thereof from the opening of the cramp-iron 16. While the further stroke is taking place, the rod moves the fork 5 with the wheel 6 into the upper working position. To ensure the reliable work of the mechanism and unloading the hydrosystem of the harrow, the fork 5 in the transport position is inclined from the vertical axis in the direction, which is opposite to the direction of movement of the unit, and is stopped by the frame. In order to ensure the precision of operation of the mechanism on the cross-arm 8 an adjusting screw 15 is mounted.