

A multistation combination actuator comprises a cylinder with front and rear caps, which with the formation of the rod and connected to the hydraulic cavities of the dispensers of the inter-piston cavity and a compensatory cavity. Placed in the cylinder the piston with the output shaft and the additional piston and rod, via which the axial cylindrical hole provided in the back cover, goes beyond it and kinematically connected to the output shaft of the stepper motor. Between the piston with an output shaft and an additional piston located intermediate piston, in which is a through axial cylindrical hole. With a hole is slidably paired the shank of the additional piston, which end with a limiter of axial displacement of the intermediate piston located concentrically in the axial bore of the output rod with the formation of a sealed secondary camera, which through the axial channel in the shank and a radial channel is made in the rod of the additional piston is connected to the channel power compensation camera.